



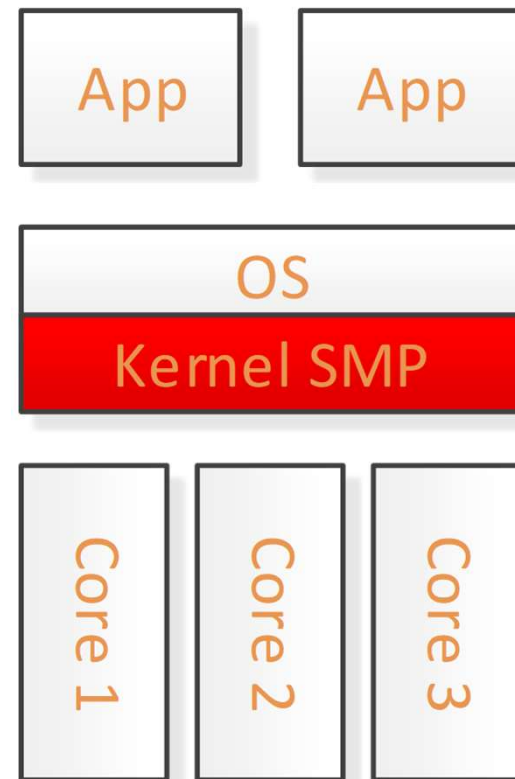
# OpenAMP

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2020.3.6



# SMP vs AMP(1)

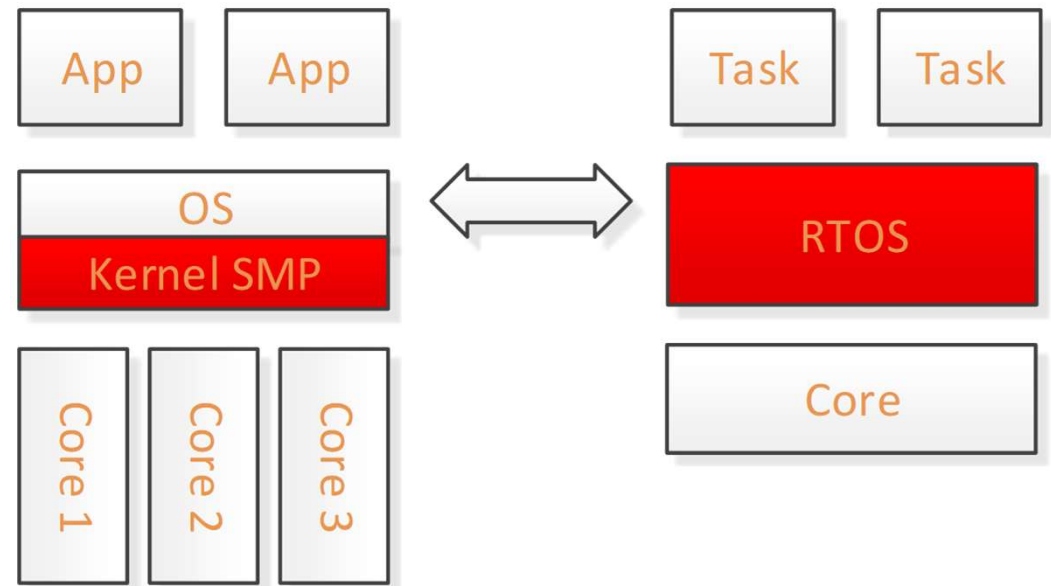
- SMP on homogeneous architectures:
  - Single OS controlling two or more identical cores sharing system resources
  - Dynamic scheduling and load balancing





## SMP vs AMP(2)

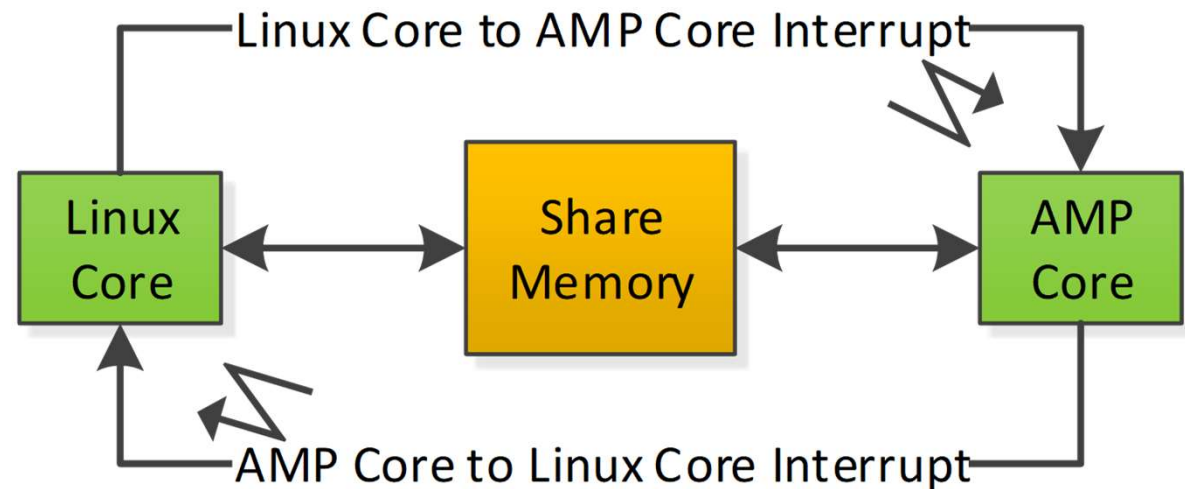
- AMP on heterogeneous architectures:
  - Different OS on each core --> full-featured OS alongside a real-time kernel
  - Inter processor communication protocol
  - Efficient when the application can be statically partitioned across cores - high performance is achieved locally





## SMP vs AMP(3)

- How does it work?
  - There is a concept of master and slave
  - Master manages shared memory
  - Master may control slave's life-cycle



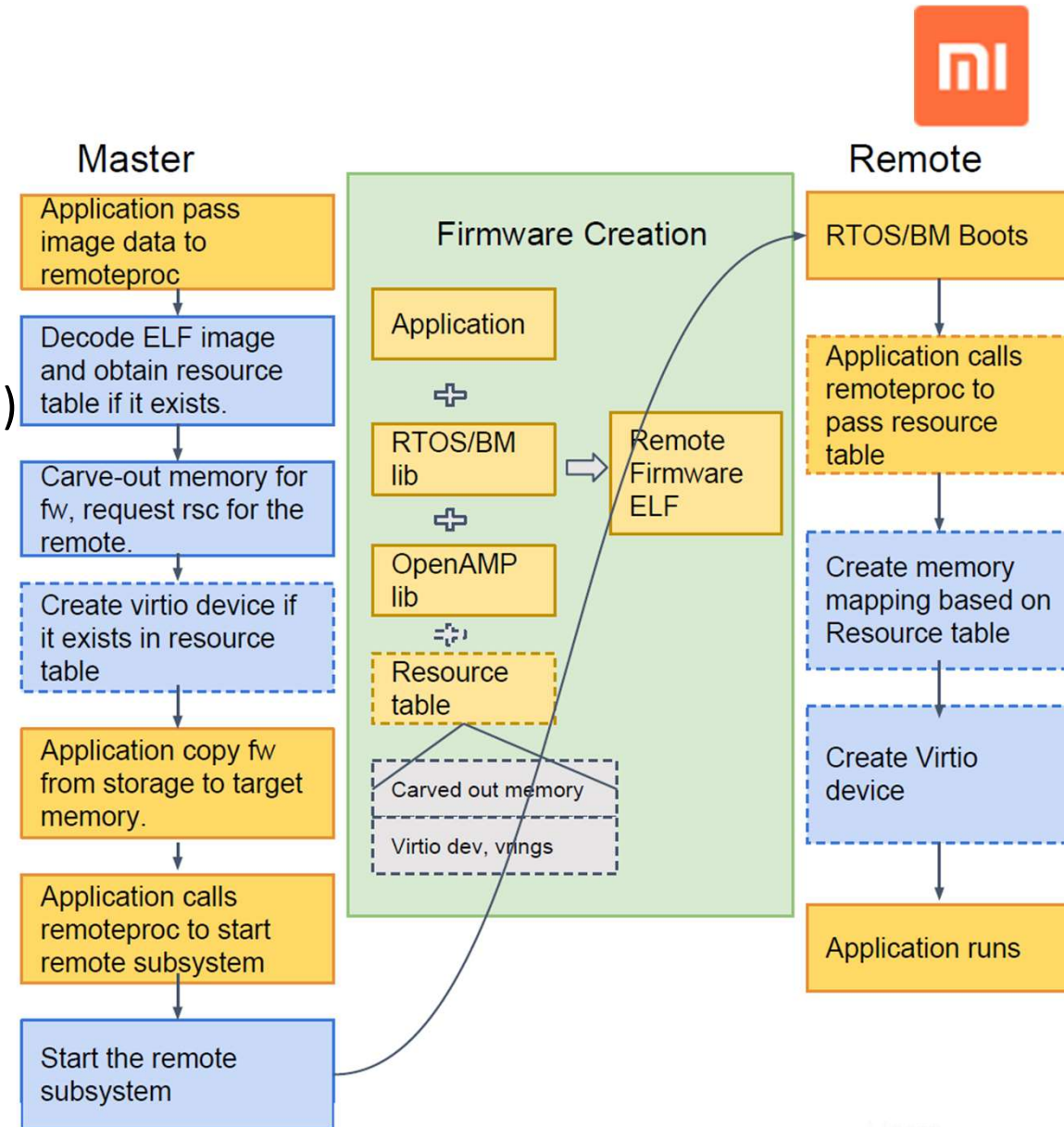


# Remoteproc(1)

- Provides user APIs to do life cycle management of the remote system and manage the resources of the remote system.
  - load remote system image
  - **setup resources for the remote system**
  - start the remote system
  - **manage the resource of the remote system**
  - **suspend the remote system**
  - **restore the remote system**
  - **stop the remote system**
  - **release the resource of the remote system**
  - shutdown the remote system and release its source

# Remoteproc(2)

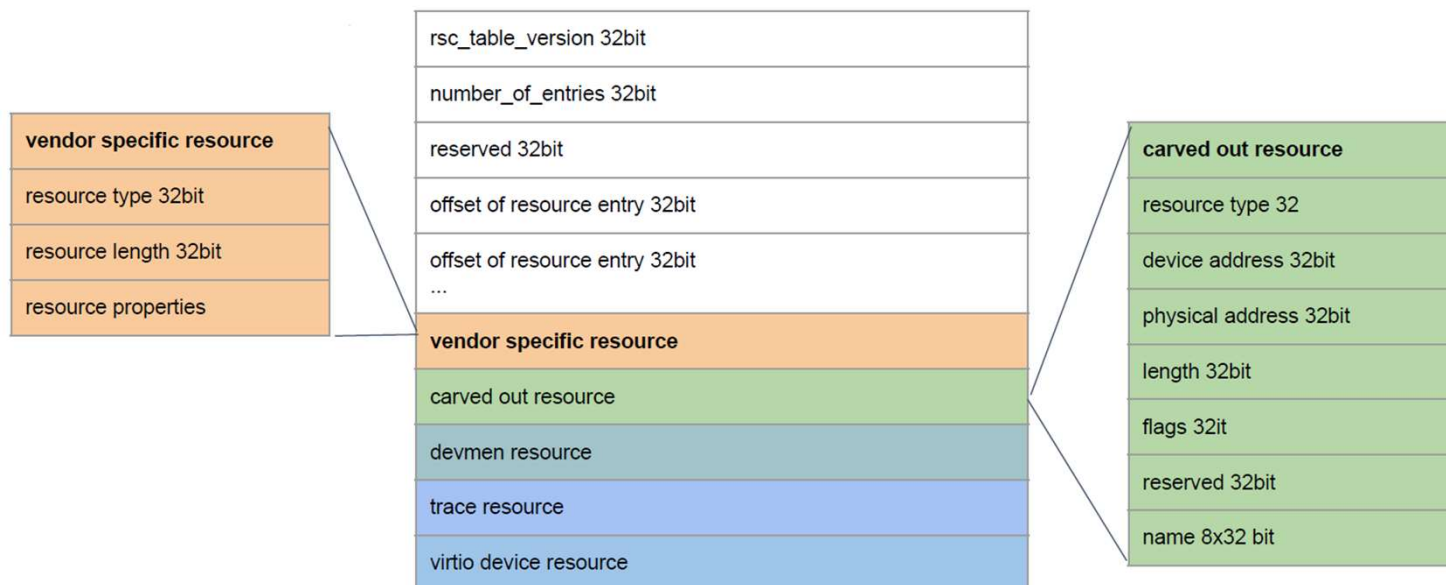
- Framework API
  - `rproc_alloc(..., ops, firmware, ...)`
  - `rproc_add()`
  - `rproc_del()`
  - `rproc_put()`
- Driver callback
  - `start()`
  - `stop()`





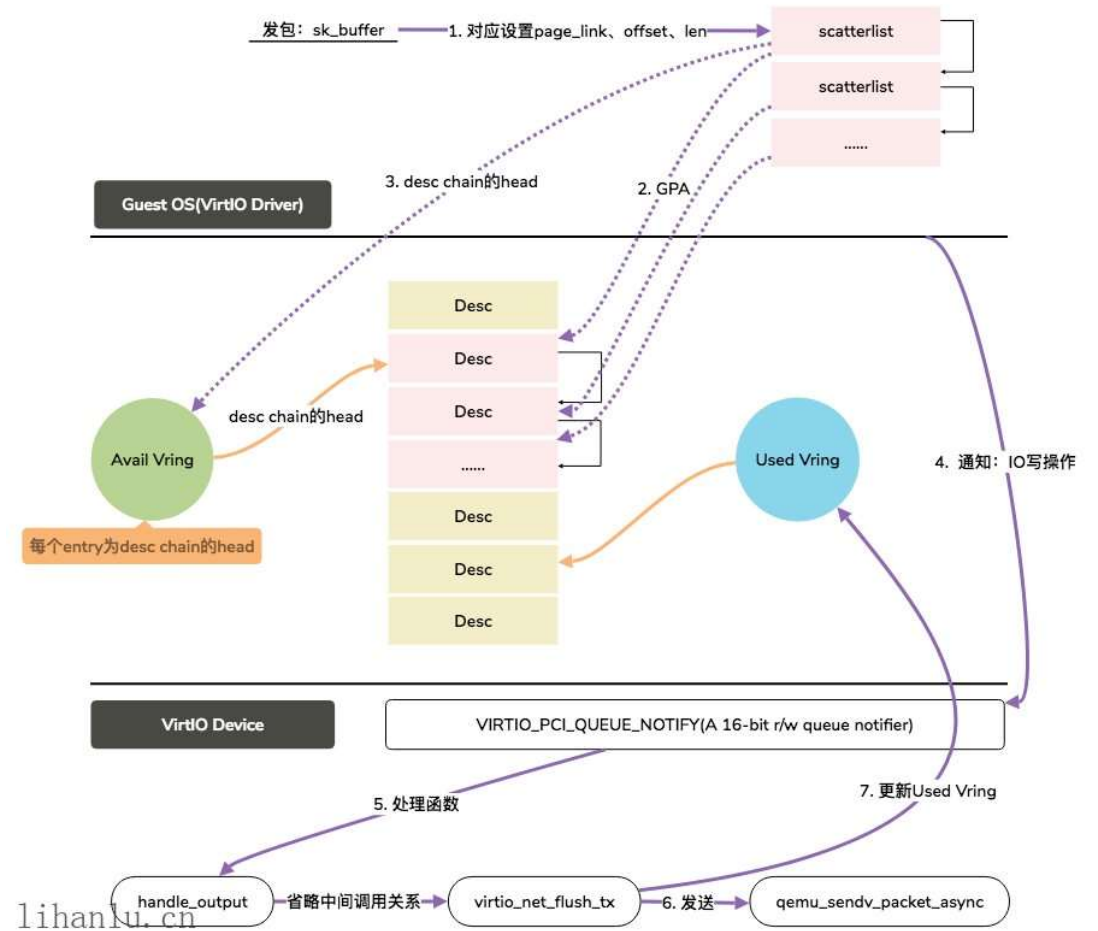
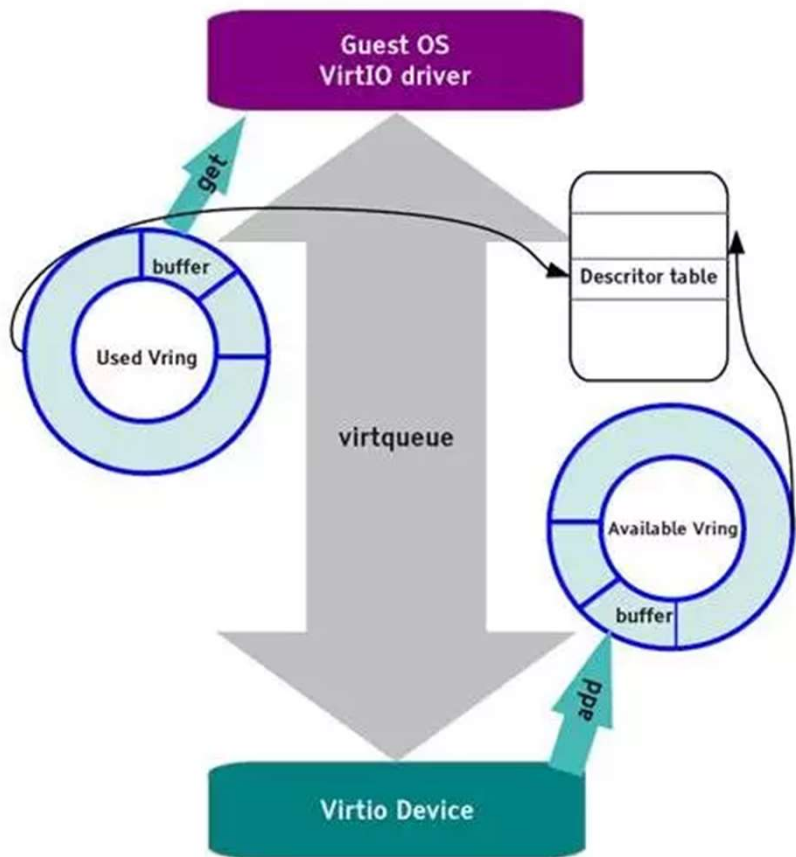
## Remoteproc(3)

- A resource table is essentially a list of system resources required by the remote system. It may also include configuration entries. e.g. virtio configuration space. If needed, the remote firmware should contain this table as a dedicated ".resource\_table" ELF section.





# Virtio(1)

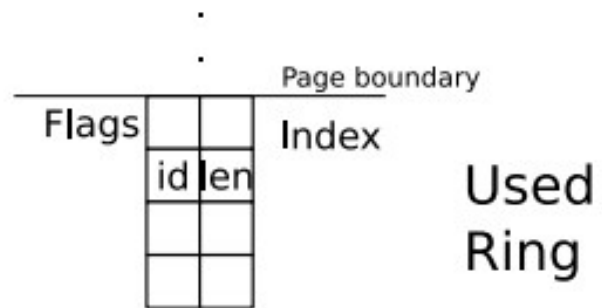
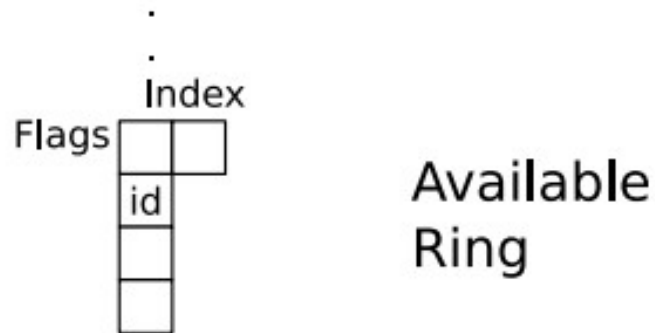
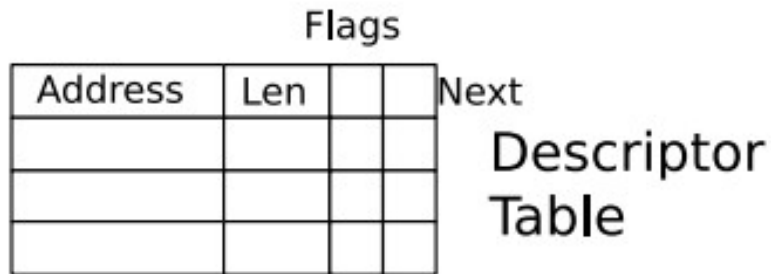


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# Virtio(2)



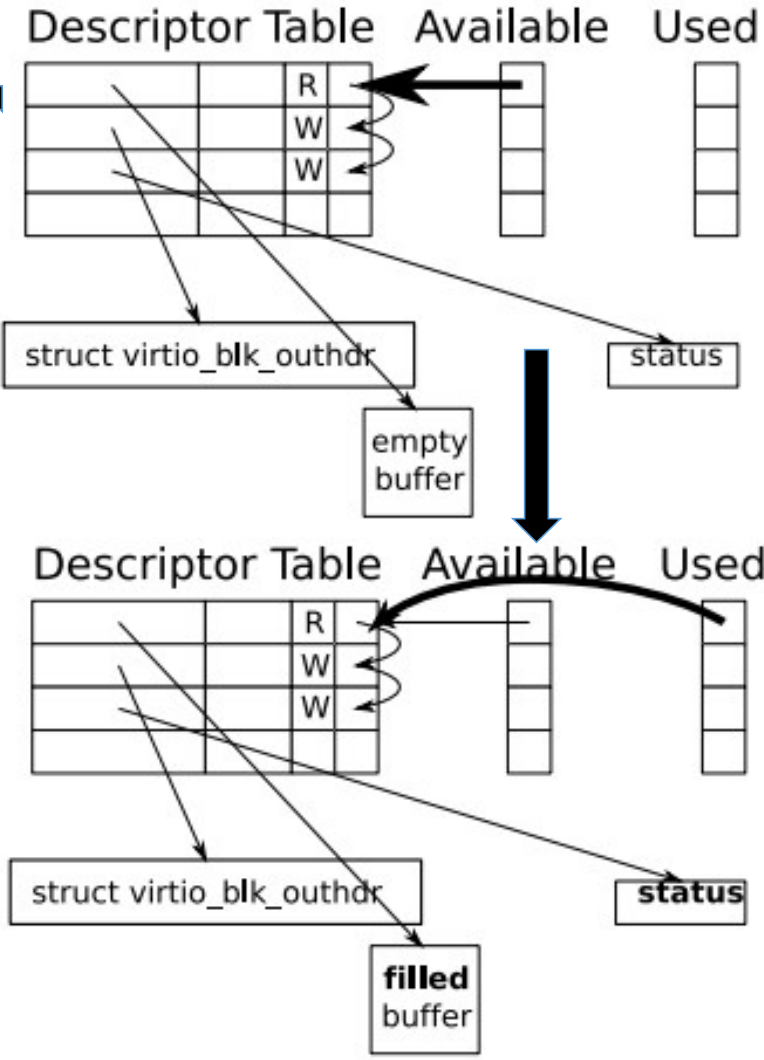
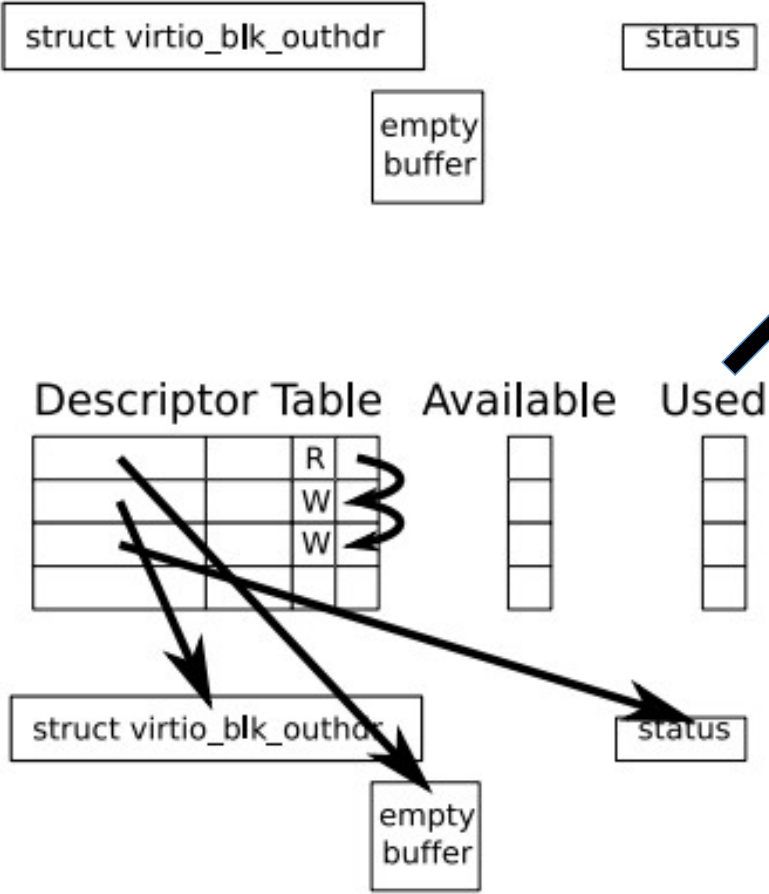
```
struct vring_desc
{
    __u64 addr;
    __u32 len;
    __u16 flags;
    __u16 next;
};
```

```
struct vring_avail
{
    __u16 flags;
    __u16 idx;
    __u16 ring[NUM];
};
```

```
struct vring_used
{
    struct vring_used_elem
    {
        __u32 id;
        __u16 flags;
        __u32 len;
    };
    __u16 idx;
    struct vring_used_elem ring[];
};
```

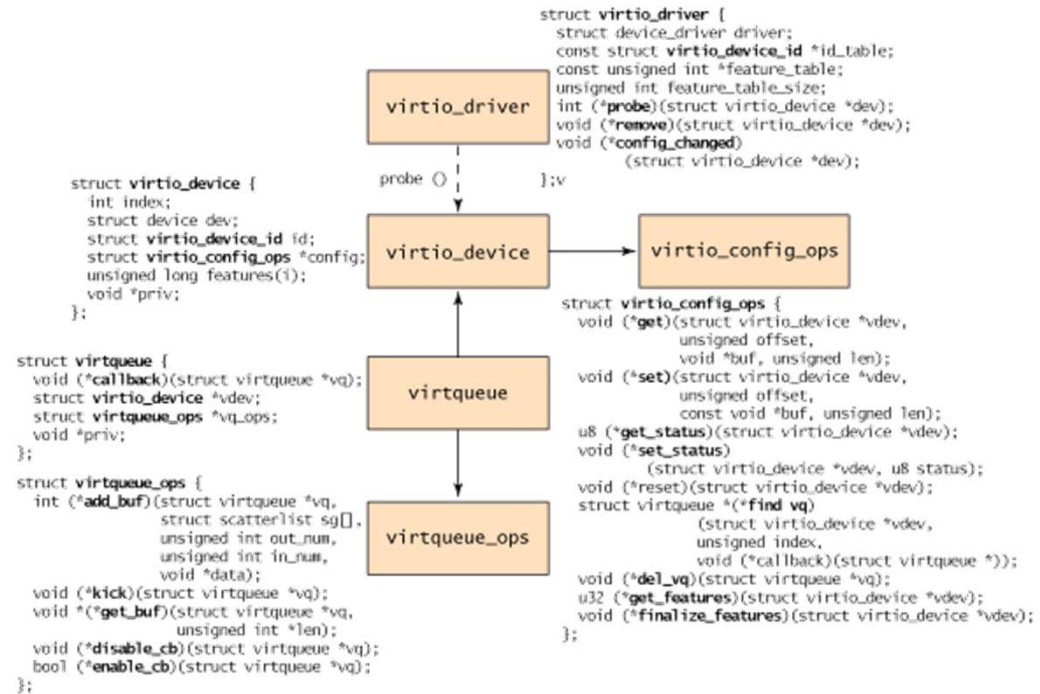
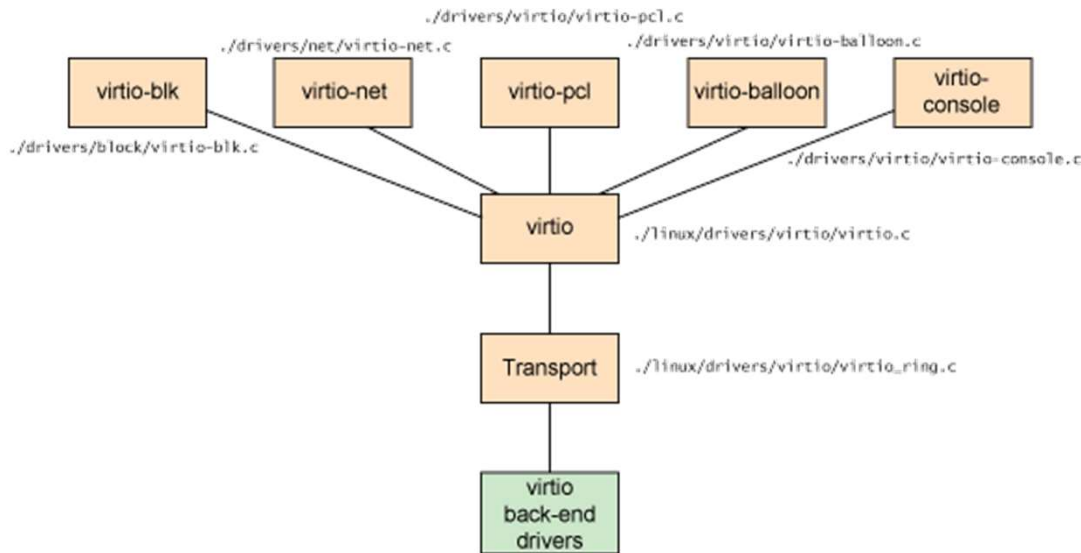


# Virtio(3)

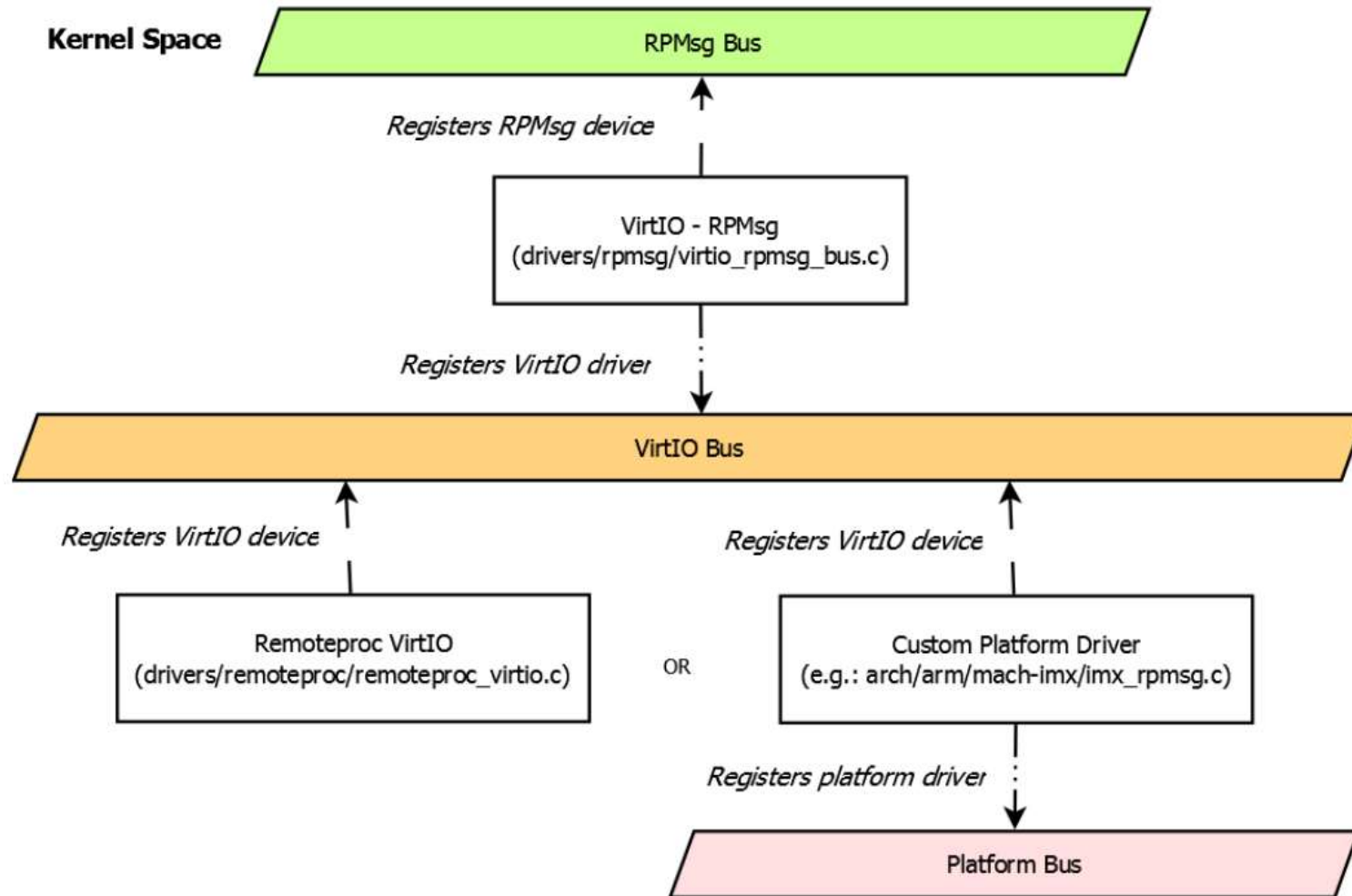




# Virtio(4)

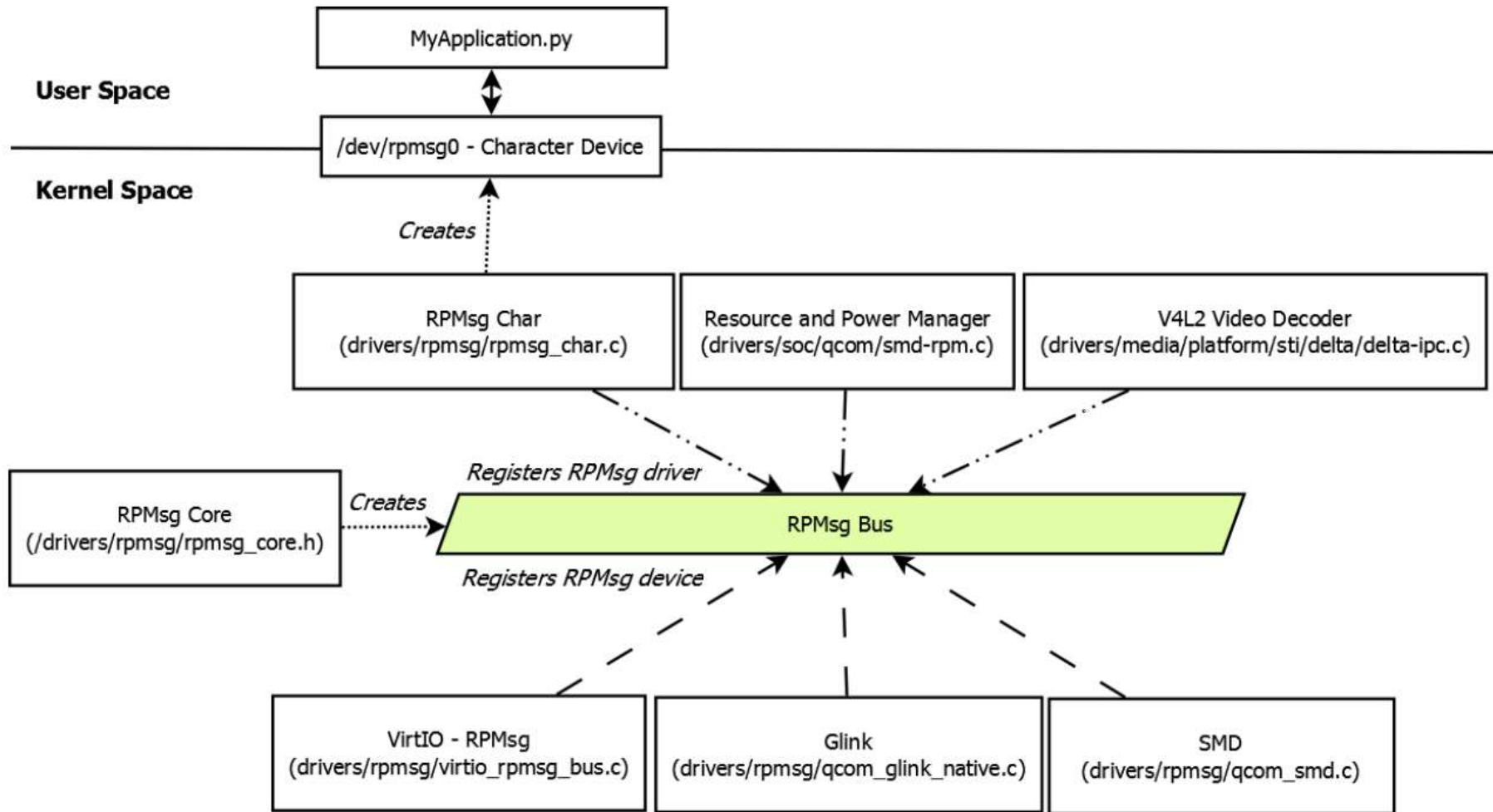


# Rpmsg(1)



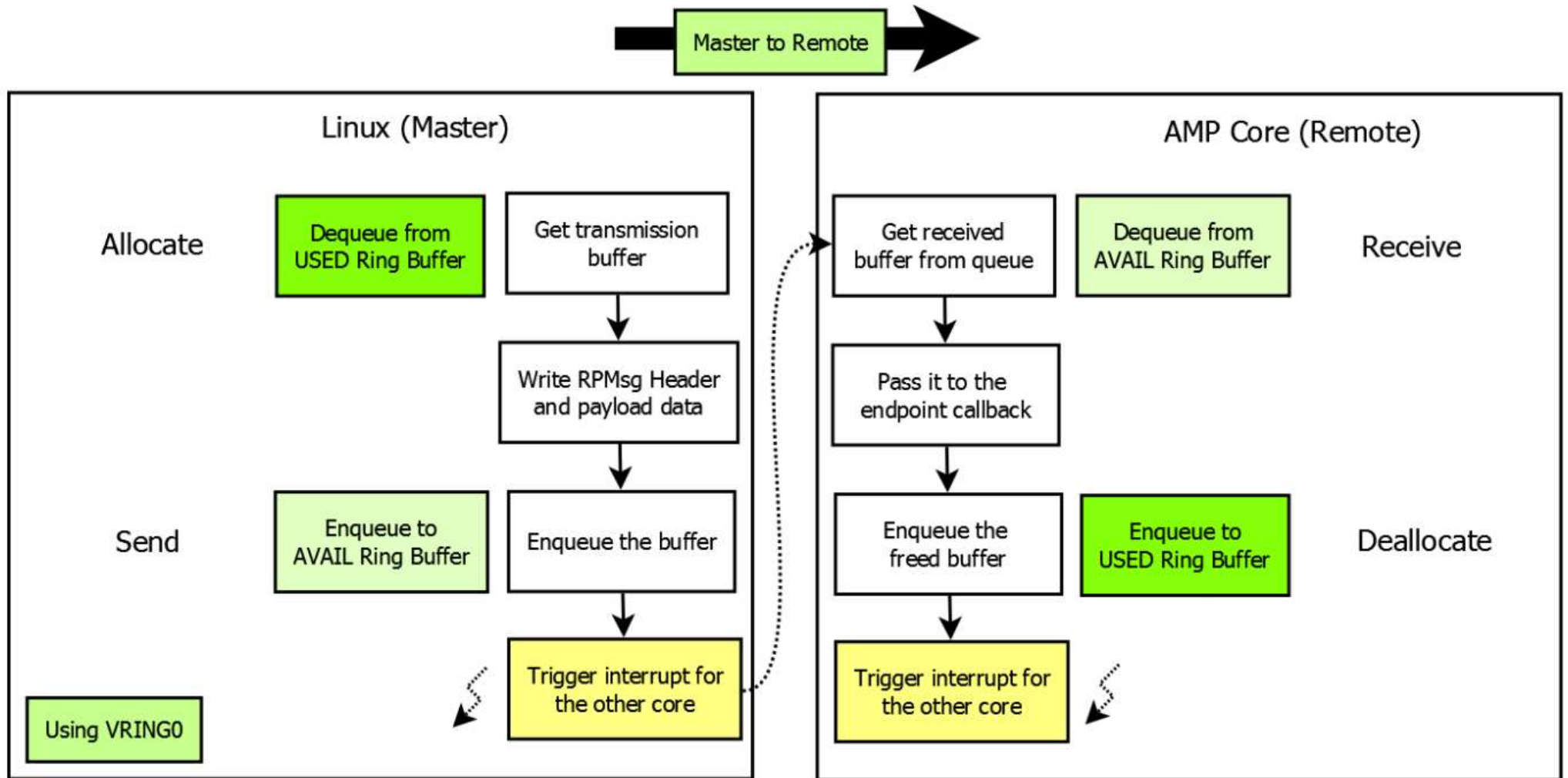


# Rpmsg(2)



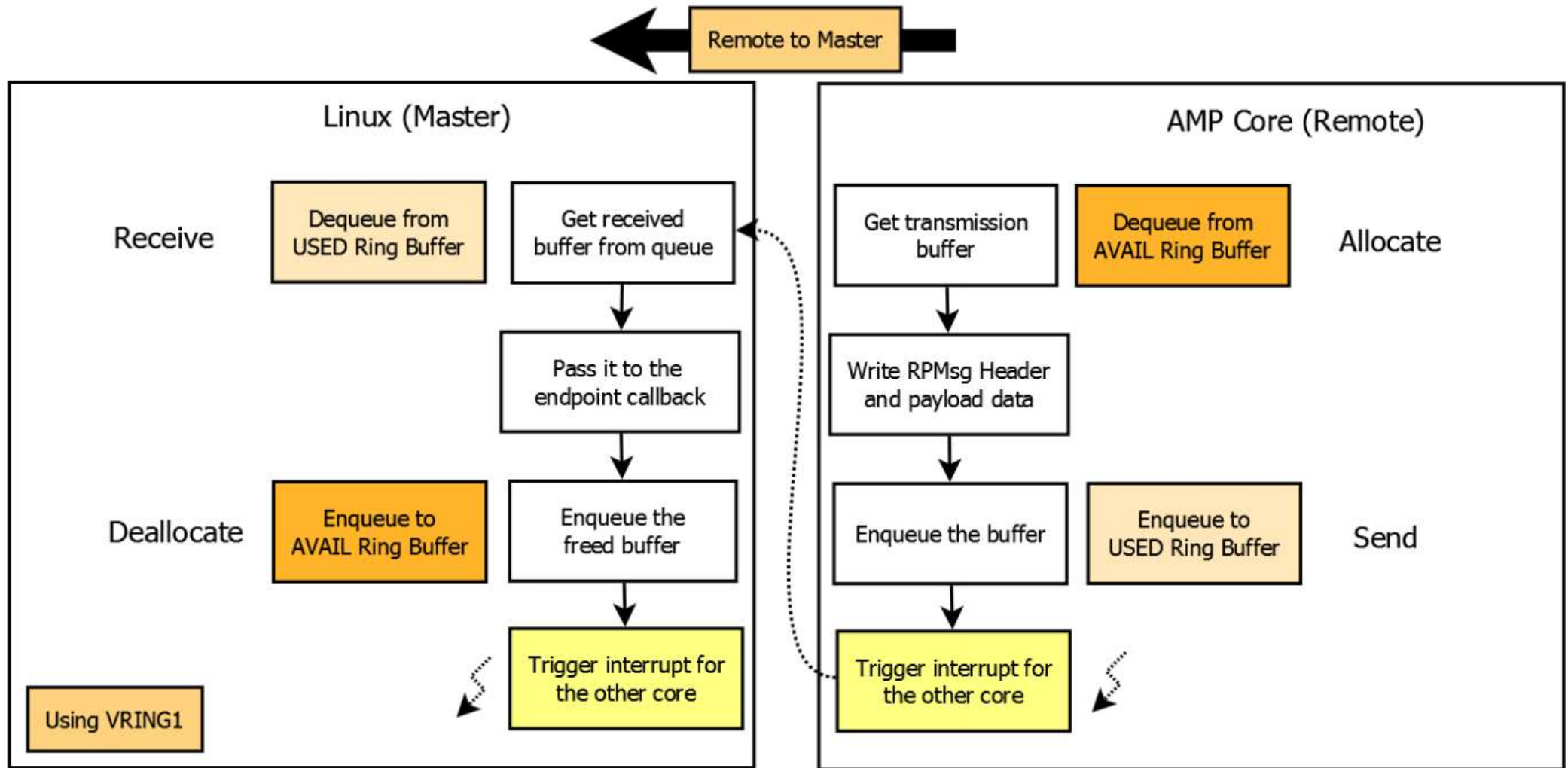


# Rpmsg(3)





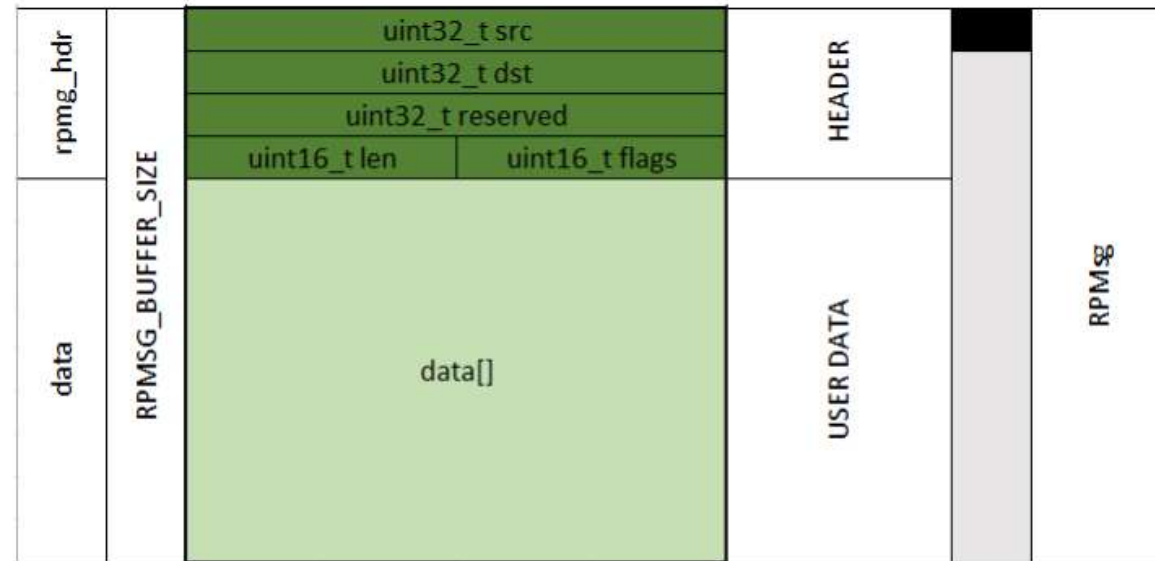
# Rpmsg(4)





# Rpmsg(5)

- Naming service
  - Convert the name to port number
  - Two phase handshake
  - Fix port number(53)



```
struct rpmsg_ns_msg {  
    char name[RPMMSG_NAME_SIZE];  
    u32 addr;  
    u32 flags;  
} __packed;
```

```
enum rpmsg_ns_flags {  
    RPMMSG_NS_CREATE = 0,  
    RPMMSG_NS_DESTROY = 1,  
    RPMMSG_NS_BIND = 2,  
    RPMMSG_NS_UNBIND = 3,  
};
```





# API(1)

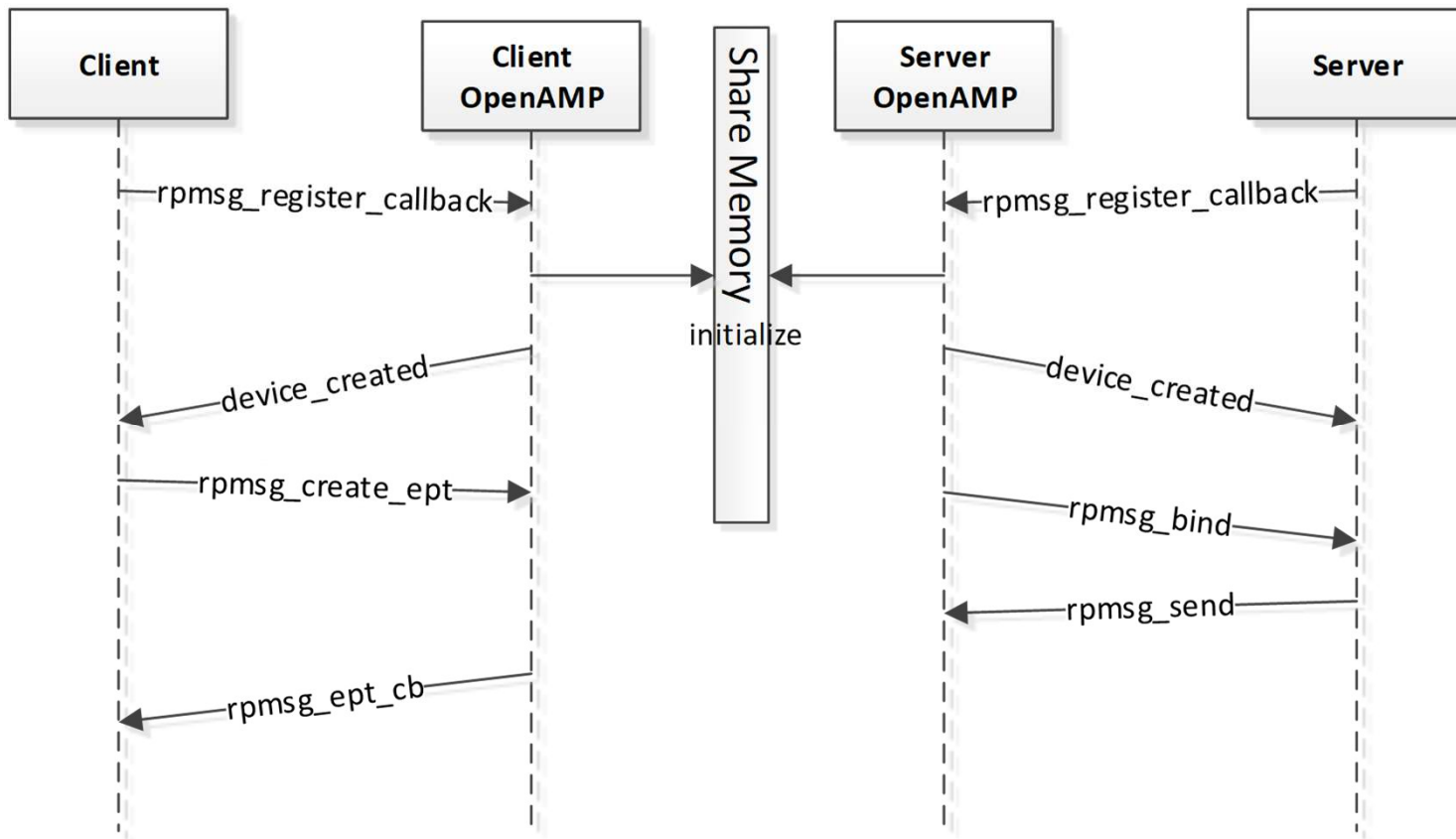
- Initialize
  - `rpmsg_register_callback`
- The peer callback
  - `device_created`
  - `device_destroyed`
- Create endpoint
  - `rpmsg_create_ept`
- The endpoint callback
  - `rpmsg_bind`



## API(2)

- Send data
  - `rpmmsg_send`
  - `rpmmsg_get_tx_payload_buffer`
  - `rpmmsg_send_nocopy`
- Receive data through callback
  - `rpmmsg_ept_cb`
  - `rpmmsg_hold_rx_buffer`
  - `rpmmsg_release_rx_buffer`

# API(3)





## API(4)

- Support the multiple remote pair
- Support the multiple channel
- The channel is identified by unique name
- Convert to the unique id for space/speed
- The channel is bidirectional
- The buffer size and number is configurable
- Don't support command/response

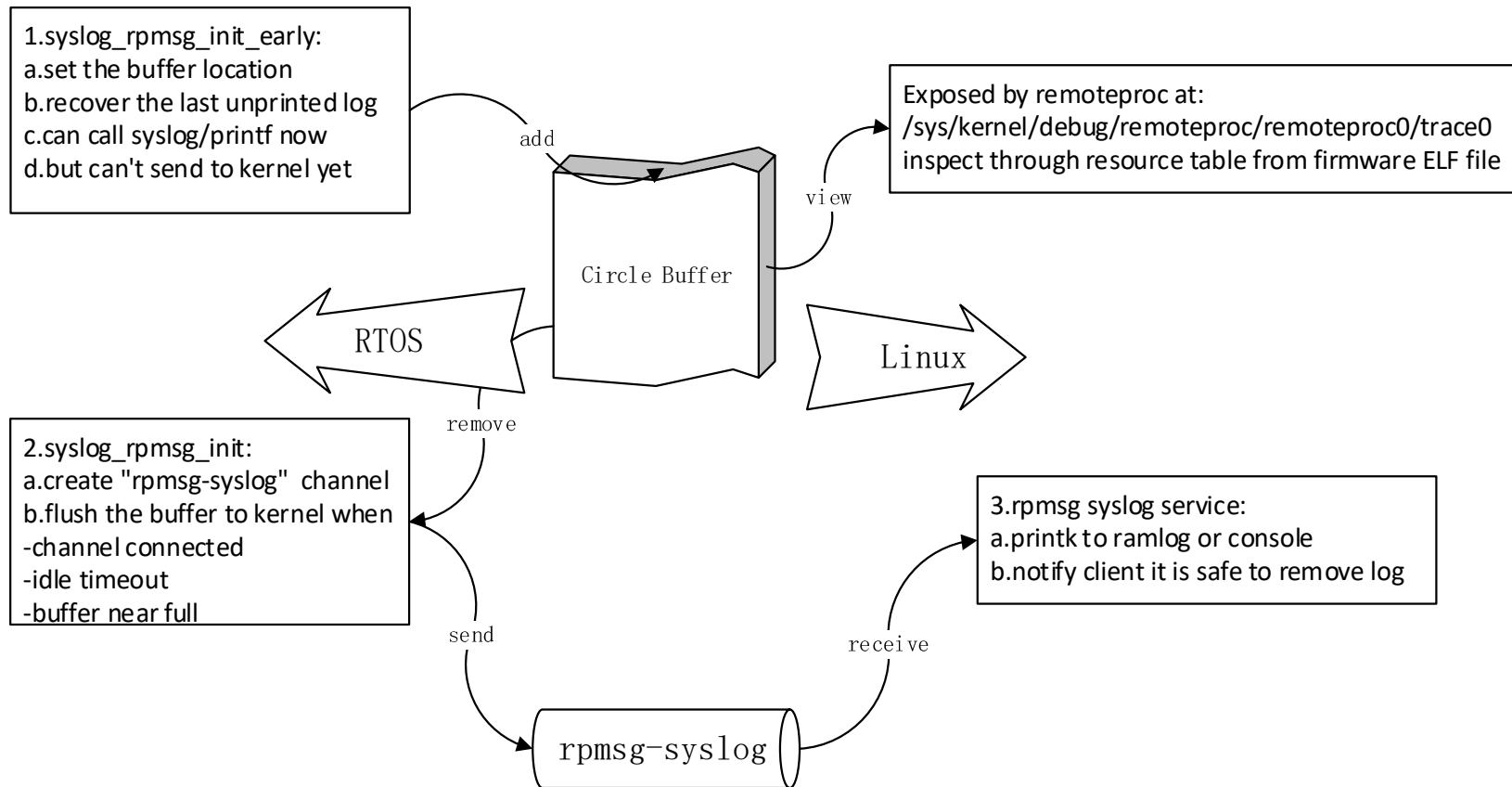


# Rpmsg Syslog(1)

- Redirect log to master core
  - Linux kernel, NuttX...
- Work as early as possible
  - Two phase initialization
- Never lost the log
  - Hang during boot or runtime
  - Full system crash(panic, watchdog...)



# Rpmsg Syslog(2)





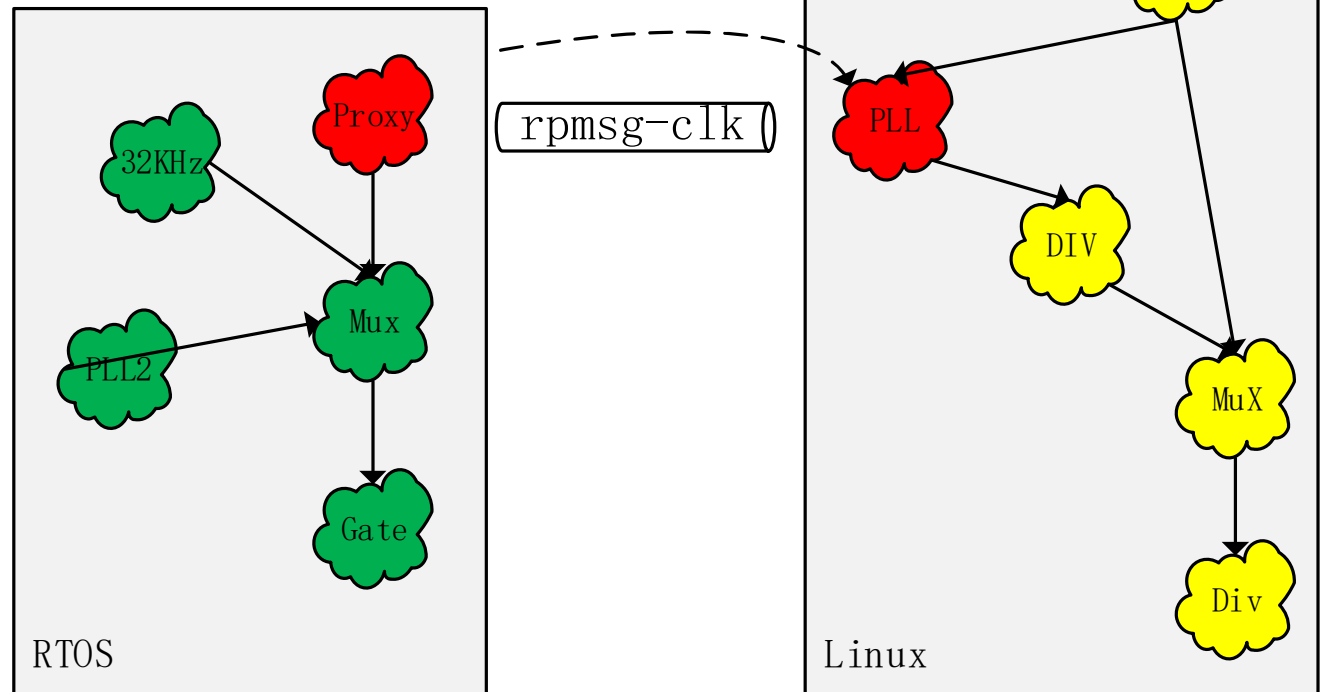
## Rpmsg TTY

- Like pseudo terminal but between two CPU
- No different from real tty(open/read/write/close)
- Full duplex communication
- Support multiple channels as need
  - Connect RTOS shell
  - Make integrated GPS like external(NMEA)
  - Make integrated modem like external(ATCMD)



# Rpmsg CLK

- Make RTOS access Linux clock framework
- Clock tree in RTOS could contain
  - The real clock
  - The rpmsg clock
  - Mix both







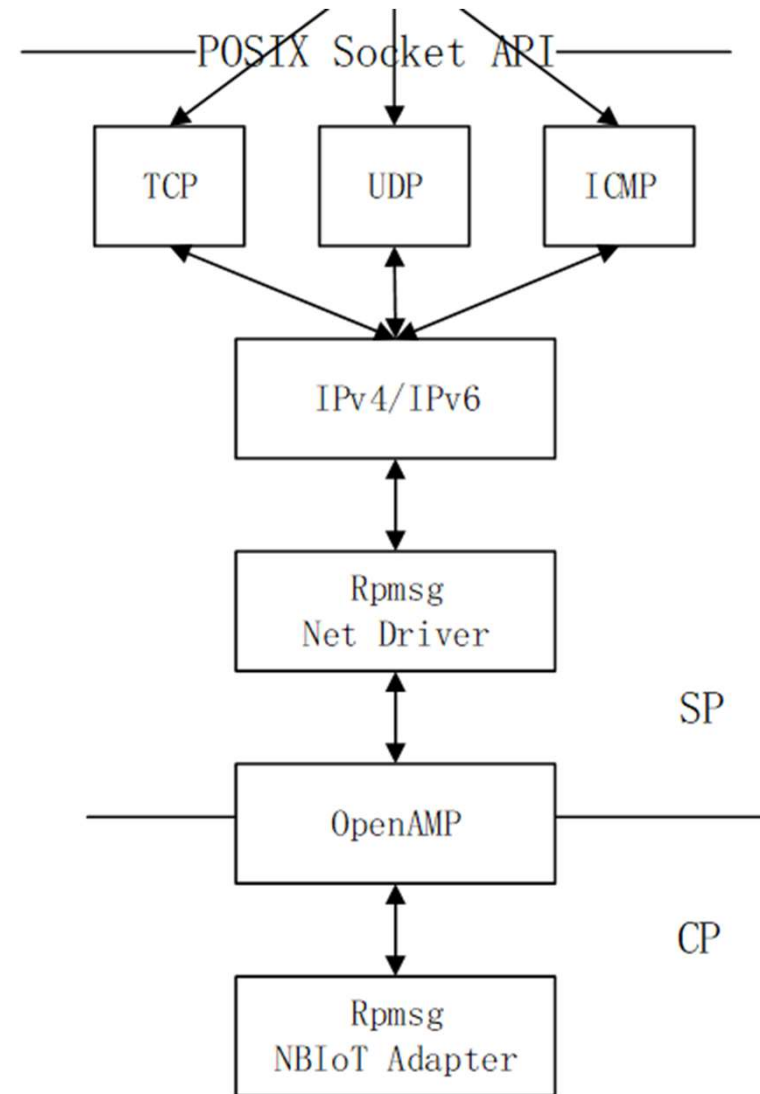
# Rpmsg HostFS

- Like NFS but between two CPU
- Fully access Host(Linux/NuttX) File system
  - Save the tuning parameter during manufacture
  - Load the tuning parameter file in production
  - Save audio dump to file for tuning/debugging
  - Dynamic loading module from host



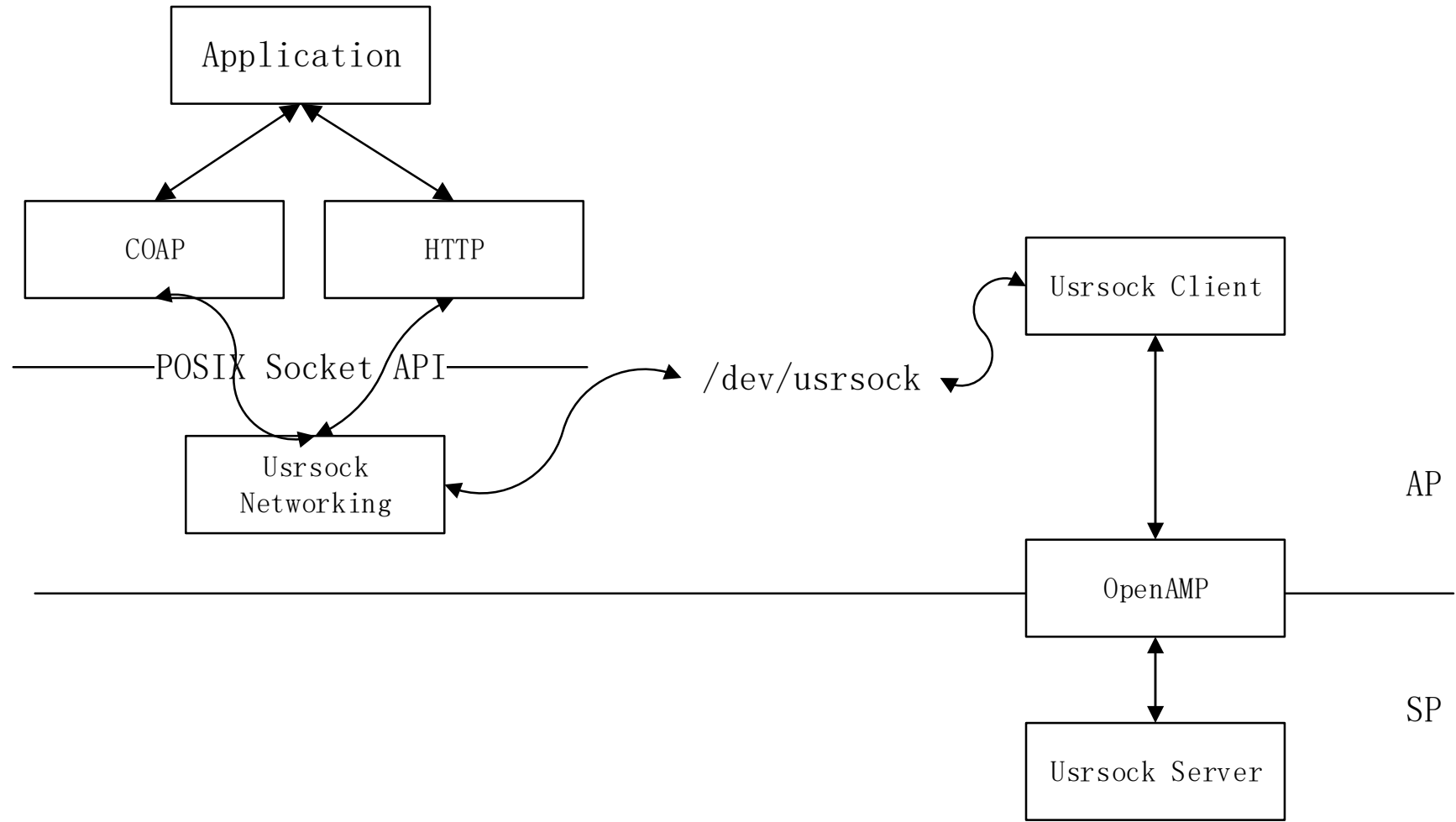
# Rpmsg Net(1)

- Rpmsg Usock Client(AP)
- Rpmsg Usock Server(SP)
- Rpmsg Net Driver(SP)
- Rpmsg NBIoT Adapter(CP)





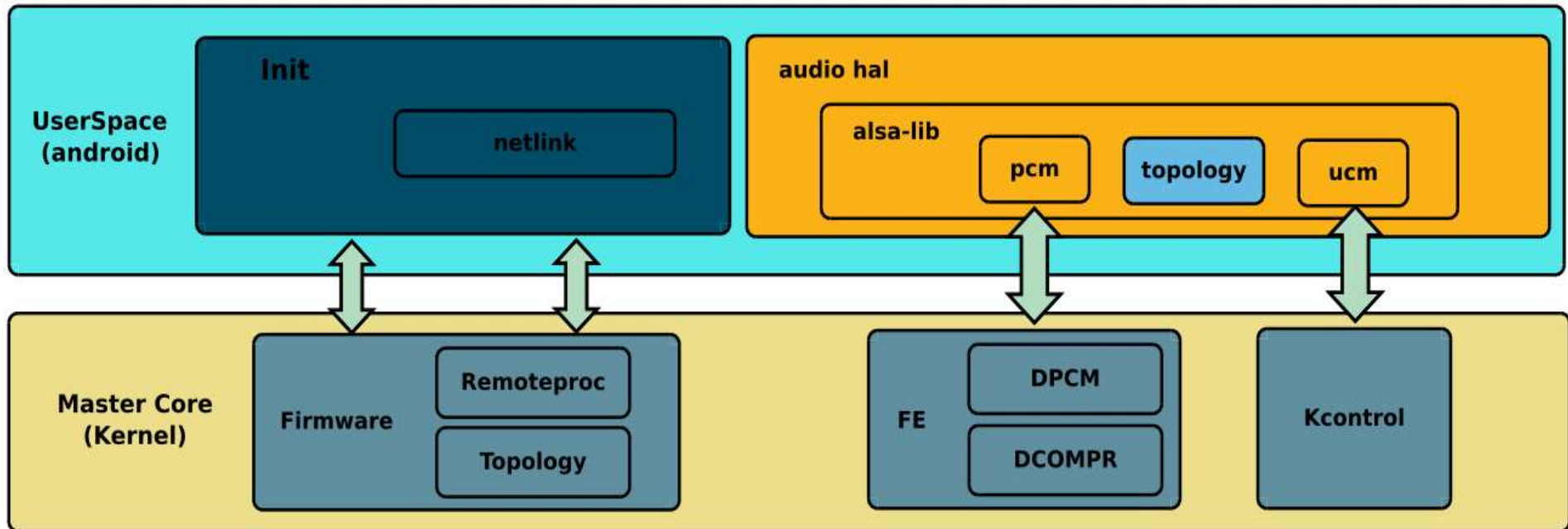
# Rpmsg Net(2)





# Audio Topology(1)

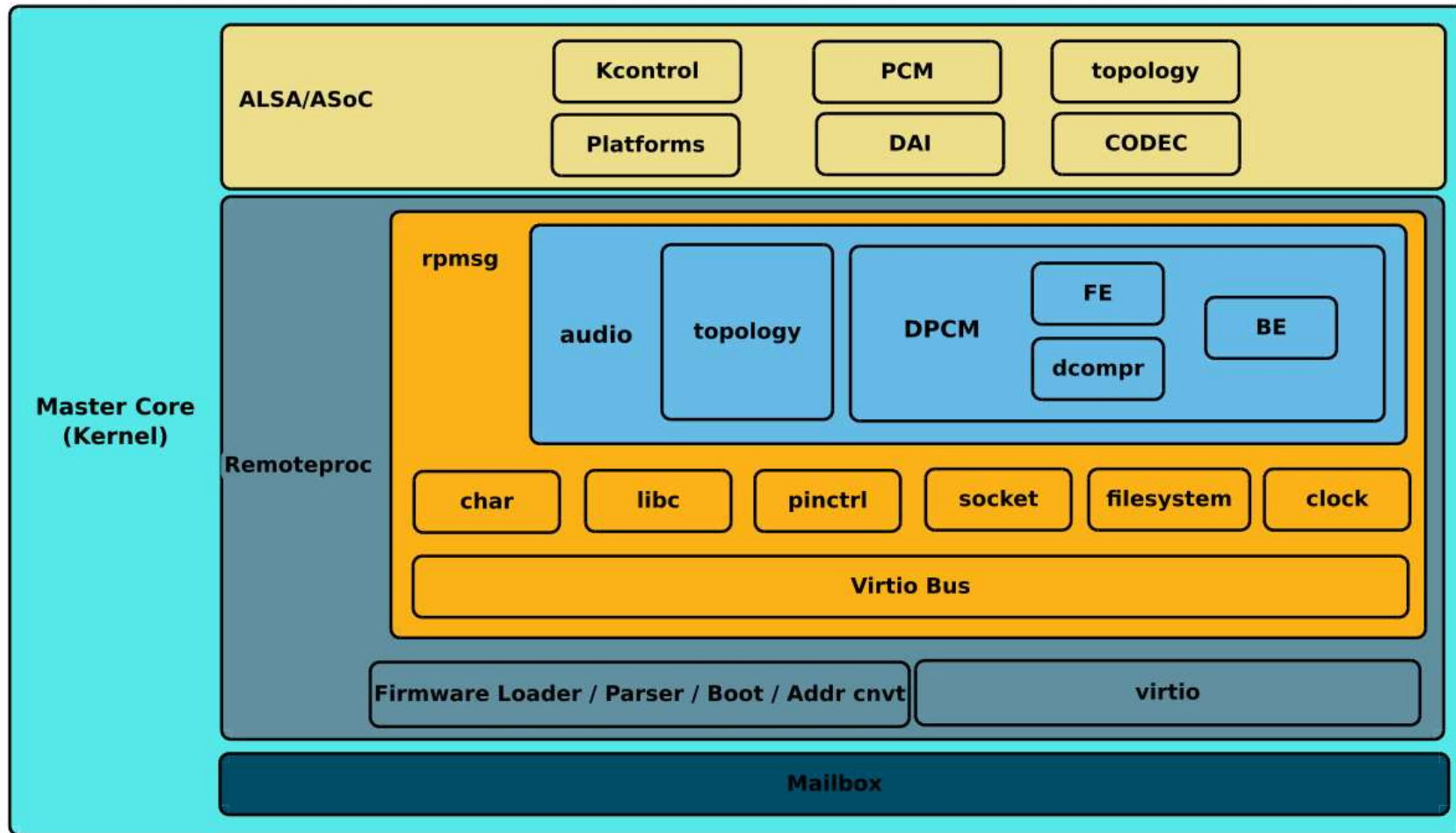
## UserSpace(android) Structure





# Audio Topology(2)

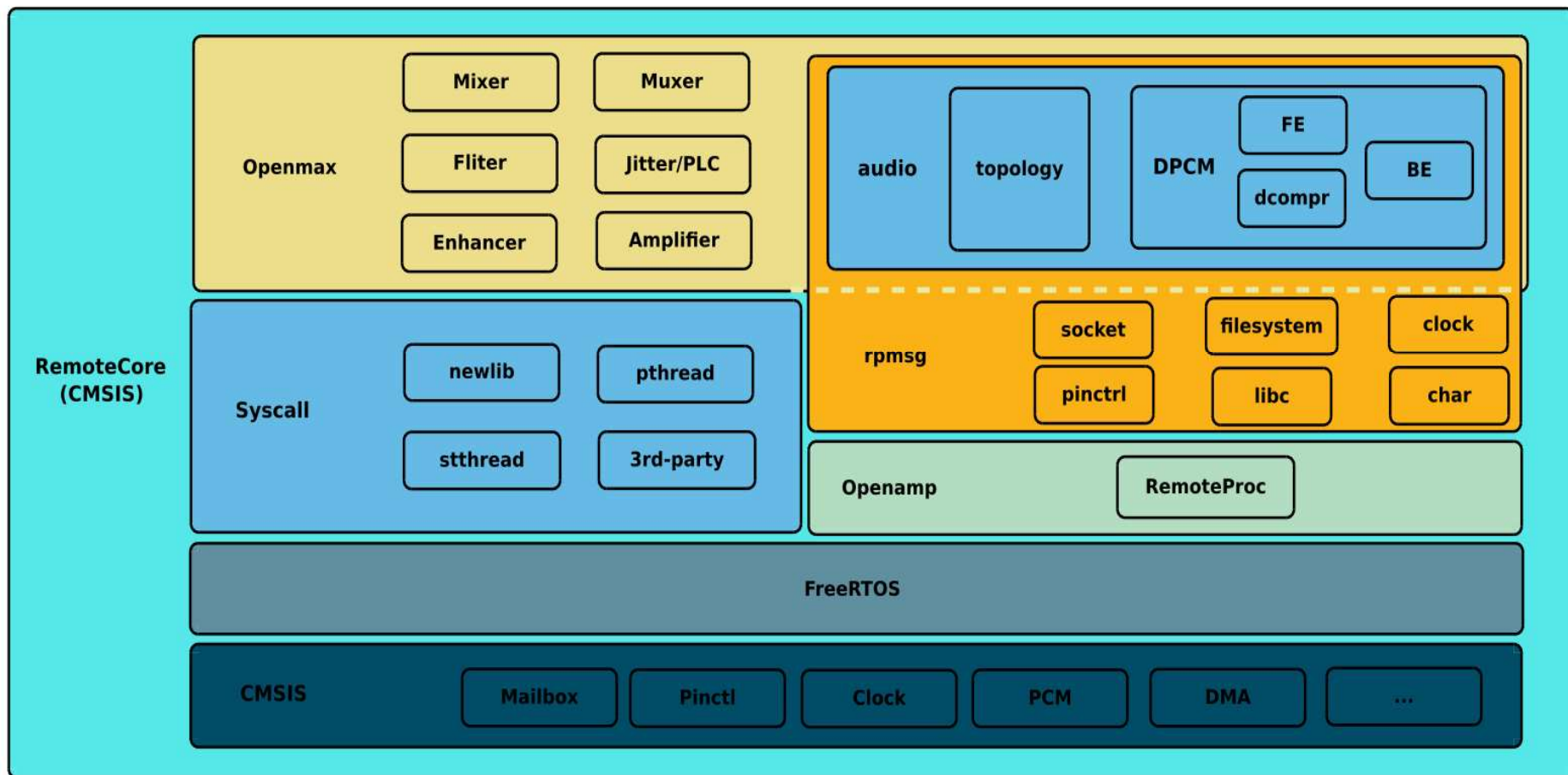
## Master Core(Kernel) Structure





# Audio Topology(3)

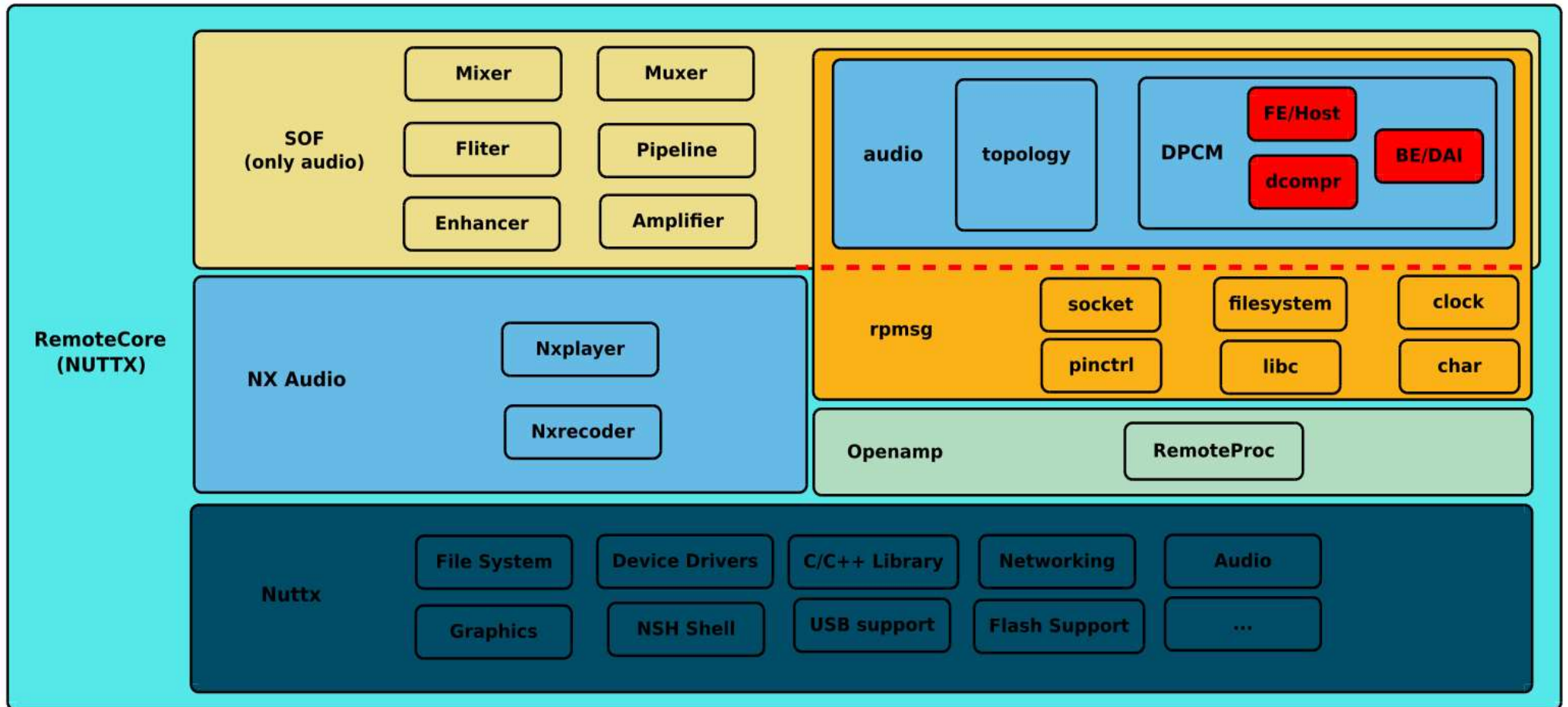
## RemoteCore(cmsis) Structure, Openmax implement





# Audio Topology(4)

## RemoteCore(NUTTX) Structure, SOF implement





# Conclusion

- It is very important and flexible to separate
  - Transport layer and Application layer
- Don't expose rpmsg channel directly
  - Encapsulate into driver/fs/net subsystem
  - No difference from real device for caller
- Enhancement
  - More proxy for regulator/pinctrl...
  - New PF\_RPMSG family for SunRPC/Protobuf...